



BSI Standards Publication

**Electrically propelled mopeds and motorcycles
— Test method for evaluating performance
of regenerative braking systems**

National foreword

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Electrically propelled mopeds and motorcycles — Test method for evaluating performance of regenerative braking systems

*À propulsion électrique cyclomoteurs et des motocycles — Méthode
d'essai pour évaluer l'efficacité du système de freinage régénératif*



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Contents

Page

Foreword	iv
1 Scope	1
2 Normative references	1
3 Terms and definitions	1
4 Principles	2
5 Test procedure for reference range gain and reference energy consumption gain	3
5.1 General	3
5.2 Reference range gain	3
5.3 Reference energy consumption gain	3
6 Test procedure for regenerative braking efficiency of traction motor system	4
6.1 Test setup	4
6.1.1 General	4
6.1.2 Load motor system	4
6.1.3 Torque and speed sensors	4
6.1.4 DC power supply	5
6.1.5 Power analyser	5
6.1.6 Voltage and current measurement	5
6.1.7 Temperature measurement	5
6.2 Test procedure	5
6.2.1 General	5
6.2.2 Steady-state regenerative braking efficiency	5
6.2.3 Transient regenerative braking efficiency measurement test	8
Annex A (informative) Test report	11
Bibliography	13

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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For an explanation on the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 38, *Motorcycles and mopeds*.

Electrically propelled mopeds and motorcycles — Test method for evaluating performance of regenerative braking systems

1 Scope

This document specifies test procedures for measuring performance of regenerative braking systems used for electric motorcycles and mopeds that are propelled by traction motors with electric batteries. Performance of regenerative braking systems is dealt with two perspectives: first, how much a regenerative braking system can extend range of a motorcycle or moped or reduce energy consumption, and second, the efficiency of the driving motor system when working as generator in regenerative braking mode.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 13064-1:2012, *Battery-electric mopeds and motorcycles — Performance — Part 1: Reference energy consumption and range*

ISO 13064-2:2012, *Battery-electric mopeds and motorcycles — Performance — Part 2: Road operating characteristics*

IEC 60034-1, *Rotating electrical machines — Part 1: Rating and performance*

IEC 60034-2-1, *Rotating electrical machines — Part 2-1: Standard methods for determining losses and efficiency from test (excluding machines for traction vehicles)*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 13064-2, IEC 60034-1, IEC 60034-2-1 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at <http://www.electropedia.org/>
- ISO Online browsing platform: available at <http://www.iso.org/obp>

3.1

load motor

electric motor that can simulate road load, as well as braking torque, when testing a *test motor system* (3.11) of electric mopeds and motorcycles

Note 1 to entry: During test, both rotational speed and torque of load motor shall be controllable within a specified range.

3.2

load motor system

combination of a *load motor* (3.1) and its inverter